

Vectors Summary

1. Scalar product (dot product):

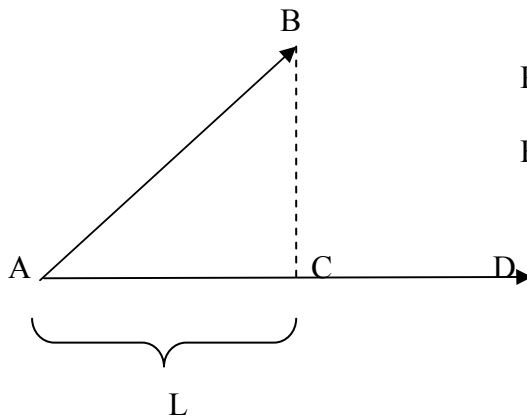
$$a \cdot b = |a| |b| \cos \theta$$

Laws of dot product:

- (i) $a \cdot b = b \cdot a$ (ii) $a \cdot (b + c) = a \cdot b + a \cdot c = b \cdot a + c \cdot a$
 (iii) $a \cdot a = |a|^2$ (angle between two identical vectors is 0 degrees)
 (iv) $a \cdot b = 0 \Rightarrow a$ and b are perpendicular

Applications:

(i) Projection vector:



$$\text{Length of projection } L = \left| \vec{AB} \cdot \hat{\vec{AD}} \right|$$

$$\text{Projection vector } \vec{AC} = (\vec{AB} \cdot \hat{\vec{AD}}) \hat{\vec{AD}}$$

$$\text{Foot of perpendicular} = \vec{OC} = \vec{OA} + \vec{AC}$$

Shortest distance from B to line

$$= |\vec{BC}|^2 = |\vec{AB}|^2 - L^2$$

$$[\text{OR} = |\vec{AB} \times \hat{\vec{AD}}|]$$

(ii) Acute angle between two lines:

$$\theta = \cos^{-1} \left(\frac{|m_1 \cdot m_2|}{|m_1| |m_2|} \right) \quad \text{where } m_1 \text{ and } m_2 \text{ are the direction vectors of the}$$

the two lines.

(iii) Acute angle between two planes:

$$\theta = \cos^{-1} \left(\frac{|n_1 \cdot n_2|}{|n_1| |n_2|} \right) \quad \text{where } n_1 \text{ and } n_2 \text{ are the individual normals to the two}$$

planes respectively.

(iv) Acute angle between a line and a plane:

$$\theta = \frac{\pi}{2} - \cos^{-1} \left(\frac{|m \cdot n|}{|m| |n|} \right) \quad \text{where } m \text{ and } n \text{ are the direction vector of the line}$$

and normal to the plane respectively, and θ is the angle between the line and plane in question.

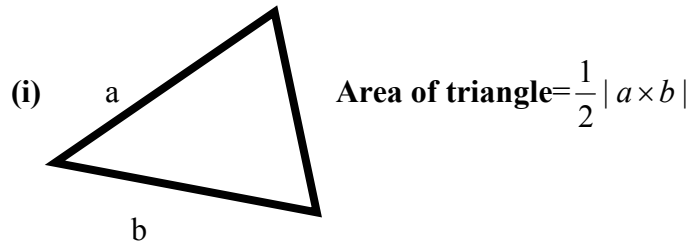
2. Cross product (vector product):

$$a \times b = [|a| |b| \sin \theta] \hat{n}$$
 where n is a vector that is perpendicular to both a and b .

Laws of cross product:

- (i) $a \times b = -(b \times a)$ (ii) $a \times (b + c) = a \times b + a \times c = -(b \times a) - (c \times a)$
(iii) $a \times a = \vec{0}$

Applications:



- (ii) If four points A, B, C and D are **coplanar**, then $|\vec{AB} \times \vec{AC}| \cdot \vec{AD} = 0$

3. Equation of lines:

Representations:

- (i) $r = \begin{pmatrix} a \\ b \\ c \end{pmatrix} + \lambda \begin{pmatrix} d \\ e \\ f \end{pmatrix}$ (parametric form) OR $r = a + \lambda m$ (condensed form)
(ii) $\frac{x-a}{d} = \frac{y-b}{e} = \frac{z-c}{f}$ (cartesian form)

4. Equations of planes:

Representations:

- (i) $r = a + \lambda m_1 + \mu m_2$ (parametric form)
(ii) $r \cdot n = a \cdot n$ (scalar product form)
(where $n = m_1 \times m_2$, a is the **position vector of a point lying on the plane.**)
(iii) $ax + by + cz = k$ (Cartesian form)
(where a, b and c are the components of the normal vector to the plane)

5. Skew lines:

Two lines with equations $r = a + \lambda m_1$ and $r = b + \mu m_2$ are said to be skew lines if they **DO NOT** intersect at a common point and m_1 is **NOT PARALLEL** to m_2 .

6. Determining if line resides in plane:

A line with equation $r = a + \lambda m$ is said to reside in the plane $r \cdot n = k$ if

- (i) $m \cdot n = 0$ (ii) $a \cdot n = k$

7. Shortest distance from plane to origin:

For a plane with equation $r \bullet n = k$, the shortest distance from the plane to the origin is given by $\left| \frac{k}{\|n\|} \right|$.

8. Distance between 2 planes:

For 2 planes with equations $r \bullet n = k_1$ and $r \bullet n = k_2$, where $|k_1| < |k_2|$, the shortest distance between them is given by:

(i) $\left| \frac{k_1}{\|n\|} + \frac{k_2}{\|n\|} \right|$ if k_1 and k_2 are of **different signs**

(ii) $\left| \frac{k_2}{\|n\|} - \frac{k_1}{\|n\|} \right|$ if k_1 and k_2 are of the **same signs**

9. Finding intersection between various constructs:

(i) Intersection between 2 lines:

For 2 lines with equations $r = a + \lambda m_1$ and $r = b + \mu m_2$, equate them to each other in column vector form such that $a + \lambda m_1 = b + \mu m_2$. Solve for the values of λ and μ before substituting back into either of the two line equations to derive the common point of intersection.

(ii) Intersection between line and plane:

For a line with equation $r = a + \lambda m$ and a plane with equation $r \bullet n = k$, substitute the line equation within that of the plane equation such that $(a + \lambda m) \bullet n = k$. Solve for the value of λ and subsequently derive the common point of intersection through substitution of λ into the line equation.

(iii) intersection between 2 planes:

A. If one plane is presented in **scalar product form** and the other in **parametric form**,

Example: $r \bullet \begin{pmatrix} 1 \\ 3 \\ 1 \end{pmatrix} = 6$ -----(1)

$$r = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + \lambda \begin{pmatrix} 3 \\ 3 \\ 1 \end{pmatrix} + \mu \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \text{-----(2)}$$

$$\Rightarrow \begin{pmatrix} 1 + 3\lambda + \mu \\ 3\lambda + \mu \\ 1 + \lambda \end{pmatrix} \bullet \begin{pmatrix} 1 \\ 3 \\ 1 \end{pmatrix} = 6$$

$$\begin{aligned}
1 + 3\lambda + \mu + 9\lambda + 3\mu + 1 + \lambda &= 6 \\
12\lambda + 4\mu &= 4 \\
3\lambda + \mu &= 1 \rightarrow \mu = 1 - 3\lambda
\end{aligned}$$

Substituting this back into (2),

Equation of line of intersection is

$$\begin{aligned}
r &= \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + \lambda \begin{pmatrix} 3 \\ 3 \\ 1 \end{pmatrix} + (1 - 3\lambda) \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \\
&= \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} + \lambda \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \quad (\text{shown})
\end{aligned}$$

B. If **both** planes are presented in **Cartesian form**:

Example: $x + y + z = 9$ -----(1)

$-x - y + z = 1$ -----(2)

(1)+(2): $2z = 10 \Rightarrow z = 5$

Let $y = t$ and substituting this together with $z = 5$ into (1),

We have $x = 4 - t$

Equation of line of intersection is

$$r = \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 4 - t \\ t \\ 5 \end{pmatrix} = \begin{pmatrix} 4 \\ 0 \\ 5 \end{pmatrix} + t \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} \quad (\text{shown})$$

C. If **both** planes are presented in **scalar product forms** or **in parametric forms** or one is presented in **scalar product form** and the **other in parametric form**, convert the plane equations such that their configurations matches that of either case A or B, and solve accordingly.

D. If a common point A with position vector a is known to reside on both planes, and the two planes have normal vectors n_1 and n_2 , then the common line of intersection is simply given by $r = a + \lambda(n_1 \times n_2)$.

(iv) Intersection between 3 planes:

Extract the components of the separate plane equations to form the **augmented matrix**:

$$r \cdot \begin{pmatrix} a_1 \\ b_1 \\ c_1 \end{pmatrix} = d_1, \quad r \cdot \begin{pmatrix} a_2 \\ b_2 \\ c_2 \end{pmatrix} = d_2, \quad r \cdot \begin{pmatrix} a_3 \\ b_3 \\ c_3 \end{pmatrix} = d_3$$

$$\downarrow$$

$$\begin{pmatrix} a_1 & b_1 & c_1 & d_1 \\ a_2 & b_2 & c_2 & d_2 \\ a_3 & b_3 & c_3 & d_3 \end{pmatrix}$$

After reducing the augmented matrix to its row reduced equivalent **using the RREF function** of the graphic calculator, 3 possible scenarios arise:

A. The planes intersect at one point, ie there is a unique solution to the matrix.

Example:

$$\begin{pmatrix} 2 & -1 & 1 & 4 \\ 1 & 2 & -2 & -3 \\ -4 & 2 & 1 & 4 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 4 \end{pmatrix}$$

$$1(x) + 0(y) + 0(z) = 1, \text{ therefore } x = 1,$$

$$0(x) + 1(y) + 0(z) = 2, \text{ therefore } y = 2,$$

$$0(x) + 0(y) + 1(z) = 4, \text{ therefore } z = 4$$

Hence, the 3 planes **intersect** at the point (1,2,4).

B. The three planes do not intersect at all.

Example:

$$\begin{pmatrix} 1 & 2 & -2 & -2 \\ -1 & 2 & -1 & 5 \\ 1 & -6 & 4 & 2 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 0 & -0.5 & 0 \\ 0 & 1 & -0.75 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

For the third row in the reduced form matrix, $0=1$, giving rise to a contradiction, hence there is no common point to the 3 planes, ie they **DO NOT intersect**.

C. The three planes intersect at a line.

Example:

$$\begin{pmatrix} 1 & 2 & -2 & -2 \\ -1 & 2 & -1 & 5 \\ 1 & -6 & 4 & -8 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 0 & -0.5 & -3.5 \\ 0 & 1 & -0.75 & 0.75 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

From the reduced row matrix, we have

$$x - \frac{1}{2}z = -\frac{7}{2} \Rightarrow x = -\frac{7}{2} + \frac{1}{2}z,$$

$$y - \frac{3}{4}z = \frac{3}{4} \Rightarrow y = \frac{3}{4} + \frac{3}{4}z$$

$$\text{Let } z = \lambda, \text{ then } \mathbf{r} = \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -\frac{7}{2} \\ \frac{3}{4} \\ 0 \end{pmatrix} + \lambda \begin{pmatrix} \frac{1}{2} \\ \frac{3}{4} \\ 1 \end{pmatrix} = \begin{pmatrix} -\frac{7}{2} \\ \frac{3}{4} \\ 0 \end{pmatrix} + \frac{1}{4}\lambda \begin{pmatrix} 2 \\ 3 \\ 4 \end{pmatrix}$$

$$\text{Therefore, the three planes **intersect** at the **line** } \mathbf{r} = \begin{pmatrix} -\frac{7}{2} \\ \frac{3}{4} \\ 0 \end{pmatrix} + t \begin{pmatrix} 2 \\ 3 \\ 4 \end{pmatrix}, \text{ where } t = \frac{\lambda}{4} \in \mathfrak{R}$$